



---

## SOME MODIFIED EXPONENTIAL RATIO-TYPE ESTIMATORS IN THE PRESENCE OF NON-RESPONSE UNDER TWO-PHASE SAMPLING SCHEME

Javid Shabbir\*, Nasir Saeed Khan

Department of Statistics, Quaid-i-Azam University, Islamabad, Pakistan.

Received 11 February 2011; Accepted 02 April 2012  
Available online 26 April 2013

**Abstract:** This paper addresses the problem of estimating the population mean using information on the auxiliary variable in the presence of non-response under two-phase sampling. On the lines of Bahl and Tuteja [1] and upadhyaya et al. [22], a class of modified exponential-ratio type estimators using single auxiliary variable have been proposed under two different situations of non-response of the study variable. The expressions for the bias and mean square error (MSE) of a proposed class of estimators are derived. Efficiency comparisons of a proposed class of estimators with the usual unbiased estimator by Hansen and Hurwitz [3] and other existing estimators are made. An empirical study has been carried out to judge the performances of the proposed estimators.

**Keywords:** Auxiliary variable, bias, mean Square error, non-response, two-phase sampling, exponential-ratio type estimator.

### 1. Introduction

Consider a finite population of size  $N$ . We draw a sample of size  $n$  from a population by using simple random sample without replacement (SRSWOR) sampling scheme. Let  $y_i$  and  $x_i$  be the observations on the study variable ( $y$ ) and the auxiliary variable ( $x$ ) respectively. Let

$\bar{y} = \sum_{i=1}^n \frac{y_i}{n}$  and  $\bar{x} = \sum_{i=1}^n \frac{x_i}{n}$  be the sample means corresponding to the population means  $\bar{Y} = \sum_{i=1}^N \frac{y_i}{N}$  and  $\bar{X} = \sum_{i=1}^N \frac{x_i}{N}$  respectively. When information on  $\bar{X}$  is unknown then double

---

\* Email: [jsqau@yahoo.com](mailto:jsqau@yahoo.com)

sampling or two phase sampling is suitable to estimate the population mean. In first phase sample we select a sample of size  $n'$  by SRSWOR from a population to observe  $x$ . In second phase, we select a sample of size  $n$  from  $n'$  ( $n < n'$ ) by SRSWOR also. Non-response occurs on second phase in which  $n_1$  units respond and  $n_2$  do not. From  $n_2$  non-respondents, a sample of  $r = n_2/k$ ;  $k > 1$  units is selected, where  $k$  is the inverse sampling rate at the second phase sample of size  $n$ .

Sometimes it may not be possible to collect the complete information for all the units selected in the sample due to non-response. Estimation of the population mean in sample surveys when some observations are missing due to non-response not at random has been considered by

Hansen and Hurwitz [3] is given by  $\bar{y}^* = w_1\bar{y}_1 + w_2\bar{y}_{2r}$ , where  $\bar{y}_1 = \sum_{i=1}^{n_1} \frac{y_i}{n_1}$ ,  $\bar{y}_{2r} = \sum_{i=1}^r \frac{y_i}{r}$ ,  $w_1 = \frac{n_1}{n}$

and  $w_2 = \frac{n_2}{n}$ .

The variance of  $\bar{y}^*$  is given by:

$$Var(\bar{y}^*) = \left(\frac{1-f}{n}\right)S_y^2 + W_2\left(\frac{k-1}{n}\right)S_{y(2)}^2, \quad (1)$$

where  $f = \frac{n}{N}$  and  $W_2 = \frac{N_2}{N}$ ,  $S_y^2 = \sum_{i=1}^N \frac{(y_i - \bar{Y})^2}{N-1}$  and  $S_{y(2)}^2 = \sum_{i=1}^{N_2} \frac{(y_i - \bar{Y}_2)^2}{N_2-1}$ .

It is well known that in estimating the population mean, sample survey experts use the auxiliary information to improve the precision of the estimates.

Similar to  $\bar{y}^*$  one can write  $\bar{x}^* = w_1\bar{x}_1 + w_2\bar{x}_{2r}$ , where  $\bar{x}_1 = \sum_{i=1}^{n_1} \frac{x_i}{n_1}$  and  $\bar{x}_{2r} = \sum_{i=1}^r \frac{x_i}{r}$ .

The variance of  $\bar{x}^*$  is given by:

$$Var(\bar{x}^*) = \left(\frac{1-f}{n}\right)S_x^2 + W_2\left(\frac{k-1}{n}\right)S_{x(2)}^2, \quad (2)$$

where  $S_x^2 = \sum_{i=1}^N \frac{(x_i - \bar{X})^2}{N-1}$  and  $S_{x(2)}^2 = \sum_{i=1}^{N_2} \frac{(x_i - \bar{X}_2)^2}{N_2-1}$ .

The auxiliary information can be used both at designing and estimation stages to compensate for units selected for a sample that fails to provide adequate responses and for the population units missing from the sampling frame. Rao ([10], [11]), Khare and Srivastava ([4], [5], [6]), Okafar and Lee [9], Sarndal and Lundstrom [12], Tabasum and Khan ([20], [21]), Singh and Kumar ([13], [14], [15], [16], [17], [18]) and Singh et al. [19] have suggested some estimators for population mean  $\bar{Y}$  of the study variable  $y$  using the auxiliary information in presence of non-response and studied their properties.

When there is non-response on the study variable  $y$  as well as on the auxiliary variable  $x$ , Cochran [2] suggested the conventional two-phase ratio and regression estimators for the population mean  $\bar{Y}$  are defined as:

$$\hat{Y}_{R(1)} = \bar{y}^* \frac{\bar{x}'}{\bar{x}^*}, \tag{3}$$

and

$$\hat{Y}_{Reg(1)} = \bar{y}^* + b_{yx}^* (\bar{x}' - \bar{x}^*), \tag{4}$$

where  $b_{yx}^* = s_{xy}^* / s_x^{*2}$  is the sample regression coefficient, whose population regression coefficient is  $\beta_{yx} = S_{xy} / S_x^2$  at the first phase sampling. Here  $s_{xy}^* = \frac{1}{(n-1)} \left( \sum_{i=1}^n x_i y_i + k \sum_{i=1}^r x_i y_i - n\bar{x} \bar{y}^* \right)$  and  $s_x^{*2} = \frac{1}{(n-1)} \left( \sum_{i=1}^n x_i^2 + k \sum_{i=1}^r x_i^2 - n\bar{x} \bar{x}^* \right)$  are the sample covariance and sample variance respectively.

Recently Singh and Kumar [17] suggested the following estimator on the lines of Bahl and Tuteja [1] as:

$$\hat{Y}_{Exp(1)} = \bar{y}^* \exp \left\{ \frac{\bar{x}' - \bar{x}^*}{\bar{x}' + \bar{x}^*} \right\}. \tag{5}$$

To the first degree of approximation, the expressions for bias and mean square error of  $\hat{Y}_{R(1)}$ ,  $\hat{Y}_{Reg(1)}$  and  $\hat{Y}_{Exp(1)}$  are given by:

$$B(\hat{Y}_{R(1)}) \cong \bar{Y} \left[ \lambda'' (1 - K_{yx}) C_x^2 + \lambda^* (1 - K_{yx(2)}) C_{x(2)}^2 \right], \tag{6}$$

$$B(\hat{Y}_{Reg(1)}) \cong \beta_{yx} \left[ \lambda'' \frac{2N^2}{(N-1)(N-2)} \left( \frac{\mu_{30(2)}}{\mu_{11}} - \frac{\mu_{21}}{\mu_{12}} \right) + \lambda^* \left( \frac{\mu_{30(2)}}{\mu_{11}} - \frac{\mu_{21(2)}}{\mu_{12}} \right) \right], \tag{7}$$

$$B(\hat{Y}_{Exp(1)}) \cong \frac{1}{2} \bar{Y} \left[ \lambda'' \left( \frac{3}{4} - K_{yx} \right) C_x^2 + \lambda^* \left( \frac{3}{4} - K_{yx(\bar{2})} \right) C_{x(2)}^2 \right], \tag{8}$$

$$MSE(\hat{Y}_{R(1)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \left\{ C_y^2 + (1 - 2K_{yx}) C_x^2 \right\} + \lambda^* \left\{ C_{y(2)}^2 + (1 - 2K_{yx(\bar{2})}) C_{x(2)}^2 \right\} \right], \tag{9}$$

$$MSE(\hat{Y}_{Reg(1)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' (1 - \rho^2) C_y^2 + \lambda^* \left\{ C_{y(2)}^2 + K_{yx} (K_{yx} - 2K_{yx(2)}) C_{x(2)}^2 \right\} \right], \tag{10}$$

$$MSE(\hat{Y}_{EXP(1)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \left\{ C_y^2 + \frac{1}{2} \left( \frac{1}{2} - 2K_{yx} \right) C_x^2 \right\} + \lambda^* \left\{ C_{y(2)}^2 + \frac{1}{2} \left( \frac{1}{2} - 2K_{yx(2)} \right) C_{x(2)}^2 \right\} \right], \quad (11)$$

where  $K_{yx} = \frac{\beta_{yx}}{R} = \frac{\rho_{yx} C_y}{C_x}$ ,  $K_{yx(2)} = \frac{\beta_{yx(2)}}{R} = \frac{\rho_{yx(2)} C_{y(2)}}{C_{x(2)}}$ ,  $\beta_{yx} = \frac{S_{yx}}{S_x^2}$ ,  $\beta_{yx(2)} = \frac{S_{yx(2)}}{S_{x(2)}^2}$ ,

$$S_{xy} = \frac{\sum_{i=1}^N (x_i - \bar{X})(y_i - \bar{Y})}{N-1}, \quad S_{xy(2)} = \frac{\sum_{i=1}^{N_2} (x_i - \bar{X}_2)(y_i - \bar{Y}_2)}{N_2-1}, \quad C_y = \frac{S_y}{\bar{Y}}, \quad C_{y(2)} = \frac{S_{y(2)}}{\bar{Y}}, \quad C_x = \frac{S_x}{\bar{X}},$$

$$C_{x(2)} = \frac{S_{x(2)}}{\bar{X}}, \quad \rho_{yx(2)} = \frac{S_{yx(2)}}{S_{x(2)} S_{y(2)}}, \quad \lambda = \left( \frac{1-f}{n} \right), \quad \lambda' = \left( \frac{1-f'}{n'} \right), \quad \lambda'' = (\lambda - \lambda'), \quad \lambda^* = \frac{W_2(k-1)}{n},$$

$$R = \frac{\bar{Y}}{\bar{X}}, \quad f = \frac{n}{N}, \quad f' = \frac{n'}{N}, \quad \mu_{vs} = \frac{1}{N-1} \sum_{i=1}^N (x_i - \bar{X})^v (y_i - \bar{Y})^s \text{ and}$$

$$\mu_{vs(2)} = \frac{1}{N_2-1} \sum_{i=1}^{N_2} (x_i - \bar{X}_2)^v (y_i - \bar{Y}_2)^s, \quad (v, s) \text{ being non-negative integers.}$$

When there is incomplete information on the study variable  $y$  and complete information on the auxiliary variable  $x$ , the conventional two-phase ratio, regression and exponential-ratio type estimators are respectively defined by:

$$\hat{Y}_{R(2)} = \bar{y}^* \frac{\bar{x}'}{\bar{x}} \quad (12)$$

and

$$\hat{Y}_{Reg(2)} = \bar{y}^* + b_{yx}^{**} (\bar{x}' - \bar{x}), \quad (13)$$

where  $b_{yx}^{**} = s_{xy}^* / s_x'^2$  is the sample regression coefficient, whose population regression coefficient is  $\beta_{yx} = S_{xy} / S_x^2$  at second phase sampling and  $s_x'^2 = \frac{1}{(n-1)} \sum_{i=1}^n (x_i - \bar{x})^2$ .

Singh and Kumar [14] defined the following exponential ratio type estimator:

$$\hat{Y}_{Exp(2)} = \bar{y}^* \exp \left\{ \frac{\bar{x}' - \bar{x}}{\bar{x}' + \bar{x}} \right\}. \quad (14)$$

To the first degree of approximation, the bias and mean square error of  $\hat{Y}_{R(2)}$ ,  $\hat{Y}_{Reg(2)}$  and  $\hat{Y}_{Exp(2)}$  are given by:

$$B(\hat{Y}_{R(2)}) \cong \bar{Y} \lambda'' (1 - K_{yx}) C_x^2, \tag{15}$$

$$B(\hat{Y}_{Reg(2)}) \cong \lambda'' \beta_{yx} \frac{2N^2}{(N-1)(N-2)} \left( \frac{\mu_{21}}{\mu_{11}} - \frac{\mu_{30}}{\mu_{20}} \right), \tag{16}$$

$$B(\hat{Y}_{EXP(2)}) \cong \frac{1}{2} \lambda'' \bar{Y} \left( \frac{3}{4} - K_{yx} \right) C_x^2, \tag{17}$$

$$MSE(\hat{Y}_{R(2)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \left\{ C_y^2 + (1 - 2K_{yx}) C_x^2 \right\} + \lambda^* C_{y(2)}^2 \right], \tag{18}$$

$$MSE(\hat{Y}_{Reg(2)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' C_y^2 (1 - \rho_{yx}^2) + \lambda^* C_{y(2)}^2 \right], \tag{19}$$

$$MSE(\hat{Y}_{EXP(2)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \left\{ C_y^2 + \frac{1}{2} (1 - 2K_{yx}) C_x^2 \right\} + \lambda^* C_{y(2)}^2 \right], \tag{20}$$

## 2. Proposed exponential-ratio type estimator

We propose the following modified exponential-ratio type estimator for estimating the populations mean  $\bar{Y}$  under two-phase sampling scheme in two different situations.

### 2.1 Situation I

The population mean  $\bar{X}$  is unknown, when non-response occurs on the study variable  $y$  and the auxiliary variable  $x$ . On the lines of Bahl and Tuteja [1] and Upadhyaya *et al.* [22], we propose the following estimator:

$$\hat{Y}_{P(1)}^{(h)} = \bar{y}^* \exp \left( \frac{c(\bar{x}' - \bar{x}^*)}{(c\bar{x}' + d) + (h-1)(\bar{x}^* - d)} \right), \tag{21}$$

where  $(h > 0)$ ;  $c (\neq 0)$  and  $d$  are constants which can be coefficient of variation ( $C_x$ ) or correlation coefficient ( $\rho_{yx}$ ) or standard deviation ( $S_x$ ).

Remarks:

- (i) When  $h = 0$ , the estimator  $\hat{Y}_{P(1)}^{(h)}$  reduces to

$$\hat{Y}_{P(1)}^{(0)} = \bar{y}^* \exp(1), \quad (22)$$

which is a biased estimator with larger *MSE* than the usual estimator  $\bar{y}^*$  due to the positive value of ‘exp’ and has multiplicative effect on the above estimator  $\hat{Y}_{P(1)}^{(0)}$ .

(ii) When  $h = 1$ , the estimator  $\hat{Y}_{P(1)}^{(h)}$  reduces to

$$\hat{Y}_{P(1)}^{(1)} = \bar{y}^* \exp\left(\frac{c(\bar{x}' - \bar{x}^*)}{c\bar{x}' + d}\right). \quad (23)$$

(iii) When  $h = 2$ , the estimator  $\hat{Y}_{P(1)}^{(h)}$  reduces to estimator:

$$\hat{Y}_{P(1)}^{(2)} = \bar{y}^* \exp\left(\frac{c(\bar{x}' - \bar{x}^*)}{(c\bar{x}' + d) + (c\bar{x}^* + d)}\right). \quad (24)$$

To obtain bias and mean square error of the estimator  $\hat{Y}_{P(1)}^{(h)}$ , we define:

$$\bar{y}^* = \bar{Y}(1 + \varepsilon_0), \quad \bar{x}^* = \bar{X}(1 + \varepsilon_1), \quad \bar{x}' = \bar{X}(1 + \varepsilon'_1), \quad \bar{x} = \bar{X}(1 + \varepsilon_2),$$

such that  $E(\varepsilon_i) = 0$ , ( $i = 0, 1, 2$ ) and  $E(\varepsilon'_i) = 0$ ,

$$\begin{aligned} E(\varepsilon_0^2) &= \lambda C_y^2 + \lambda^* C_{y(2)}^2, \quad E(\varepsilon_1^2) = \lambda C_x^2 + \lambda^* C_{x(2)}^2, \quad E(\varepsilon_1'^2) = \lambda' C_x^2, \quad E(\varepsilon_2^2) = \lambda C_x^2, \\ E(\varepsilon_0 \varepsilon_1) &= \lambda \rho_{yx} C_y C_x + \lambda^* \rho_{yx(2)} C_{y(2)} C_{x(2)}, \quad E(\varepsilon_0 \varepsilon_1') = \lambda' \rho_{yx} C_y C_x, \quad E(\varepsilon_0 \varepsilon_2) = \lambda \rho_{yx} C_y C_x, \\ E(\varepsilon_1 \varepsilon_1') &= \lambda' C_x^2, \quad E(\varepsilon_1 \varepsilon_2) = \lambda C_x^2 \text{ and } E(\varepsilon_1' \varepsilon_2) = \lambda' C_x^2. \end{aligned}$$

Expressing the estimator  $\hat{Y}_{P(1)}^{(h)}$  given in (21), in terms of  $\varepsilon$ 's, we have:

$$\hat{Y}_{P(1)}^{(h)} = \bar{Y}(1 + \varepsilon_0) \exp\left(\frac{(\varepsilon_1' - \varepsilon_1)}{(\varepsilon_1' + (h-1)\varepsilon_1 + h\delta)}\right), \quad (25)$$

$$\text{where } \delta = \left(\frac{c\bar{X} + d}{c\bar{X}}\right).$$

Solving (25), neglecting terms of  $\varepsilon$ 's having power greater than two, we have:

$$(\hat{Y}_{P(1)}^{(h)} - \bar{Y}) \cong \bar{Y} \left[ \varepsilon_0 + \frac{1}{h\delta} (\varepsilon_1' - \varepsilon_1) + \frac{1}{h\delta} (\varepsilon_0 \varepsilon_1' - \varepsilon_0 \varepsilon_1) \right]$$

$$+ \frac{1}{h^2 \delta^2} (\varepsilon'_1 - \varepsilon_1)^2 - \frac{1}{h^2 \delta^2} (\varepsilon_1'^2 + (h-2) \varepsilon'_1 \varepsilon_1 - (h-1) \varepsilon_1^2) \Big]. \tag{26}$$

Taking expectations on both sides of (26), we get the bias of  $\hat{Y}_{P(1)}^{(h)}$  which is given by:

$$B(\hat{Y}_{P(1)}^{(h)}) \cong \bar{Y} \left[ \lambda'' \frac{1}{h\delta} \left\{ \frac{1}{h\delta} \left( h - \frac{1}{2} \right) - K_{yx} \right\} C_{x^2}^2 + \lambda^* \frac{1}{h\delta} \left\{ \frac{1}{h\delta} \left( h - \frac{1}{2} \right) - K_{yx(2)} \right\} C_{x(2)}^2 \right]. \tag{27}$$

Squaring both sides of (26) and neglecting terms of  $\varepsilon$ 's involving power greater than two, we have:

$$(\hat{Y}_{P(1)}^{(h)} - \bar{Y})^2 \cong \bar{Y}^2 \left[ \varepsilon_0^2 + \frac{1}{h^2 \delta^2} (\varepsilon_1'^2 + \varepsilon_1^2 - 2\varepsilon'_1 \varepsilon_1) + \frac{2}{h\delta} (\varepsilon_0 \varepsilon'_1 - \varepsilon_0 \varepsilon_1) \right]. \tag{28}$$

Using (28), the *MSE* of  $\hat{Y}_{P(1)}^{(h)}$  to the first degree approximation is given by:

$$MSE(\hat{Y}_{P(1)}^{(h)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \{ C_y^2 + A_1 C_x^2 \} + \lambda^* \{ C_{y(2)}^2 + A_2 C_{x(2)}^2 \} \right], \tag{29}$$

where  $A_1 = \frac{1}{h\delta} \left( \frac{1}{h\delta} - 2K_{yx} \right)$  and  $A_2 = \frac{1}{h\delta} \left( \frac{1}{h\delta} - 2K_{yx(2)} \right)$ .

The *MSE*( $\hat{Y}_{P(1)}^{(h)}$ ) is minimum when  $h = \frac{\lambda'' C_x^2 + \lambda^* C_{x(2)}^2}{\left\{ \lambda'' K_{yx} C_x^2 + \lambda^* K_{yx(2)} C_{x(2)}^2 \right\} \delta} = h_0$  (say).

Thus the resulting minimum *MSE* of  $\hat{Y}_{P(1)}^{(h)}$  is given by:

$$MSE(\hat{Y}_{P(1)}^{(h)})_{\min} \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' C_y^2 + \lambda^* C_{y(2)}^2 - \frac{(\lambda'' C_x^2 + \lambda^* C_{x(2)}^2)^2}{\lambda'' K_{yx} C_x^2 + \lambda^* K_{yx(2)} C_{x(2)}^2} \right]. \tag{30}$$

Table 1 shows some members of a proposed class of estimators  $\hat{Y}_{P(1)}^{(h)}$  of the population mean  $\bar{Y}$  by taking  $h = 1$  and  $h = 2$ , each at different values of  $c$  and  $d$ . Many more estimators can also be generated from the proposed estimator in (21) just by taking different values of  $h$ ,  $c$  and  $d$ .

Table 1. Some members of a family of estimators  $\hat{Y}_{P(1)}^{(h)}$  under Situation-I.

Estimator	$h$	$c$	$d$
$\hat{Y}_{P(1)}^{(1)(1)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}^*}{\bar{x}' + S_x}\right)$	1	1	$S_x$
$\hat{Y}_{P(1)}^{(1)(2)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}^*}{\bar{x}' + C_x}\right)$	1	1	$C_x$
$\hat{Y}_{P(1)}^{(1)(3)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}^*}{\bar{x}' + \rho_{yx}}\right)$	1	1	$\rho_{yx}$
$\hat{Y}_{P(1)}^{(1)(4)} = \bar{y}^* \exp\left(\frac{C_x(\bar{x}' - \bar{x}^*)}{C_x \bar{x}' + S_x}\right)$	1	$C_x$	$S_x$
$\hat{Y}_{P(1)}^{(2)(1)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}^*}{(\bar{x}' + S_x) + (\bar{x}^* + S_x)}\right)$	2	1	$S_x$
$\hat{Y}_{P(1)}^{(2)(2)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}^*}{(\bar{x}' + C_x) + (\bar{x}^* + C_x)}\right)$	2	1	$C_x$
$\hat{Y}_{P(1)}^{(2)(3)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}^*}{(\bar{x}' + \rho_{yx}) + (\bar{x}^* + \rho_{yx})}\right)$	2	1	$\rho_{yx}$
$\hat{Y}_{P(1)}^{(2)(4)} = \bar{y}^* \exp\left(\frac{C_x(\bar{x}' - \bar{x}^*)}{(C_x \bar{x}' + S_x) + (C_x \bar{x}^* + S_x)}\right)$	2	$C_x$	$S_x$

The expressions of mean square error of the above estimators (Table 1) are given by:

$$MSE(\hat{Y}_{P(1)}^{(1)(i)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \{C_y^2 + A_3 C_x^2\} + \lambda^* \{C_{y(2)}^2 + A_4 C_{x(2)}^2\} \right], \quad (31)$$

where  $A_3 = \frac{1}{\delta_i} \left( \frac{1}{\delta_i} - 2K_{yx} \right)$  and  $A_4 = \frac{1}{\delta_i} \left( \frac{1}{\delta_i} - 2K_{yx(2)} \right)$  ( $i = 1, 2, 3, 4$ ) and

$$MSE(\hat{Y}_{P(1)}^{(2)(i)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \{C_y^2 + A_5 C_x^2\} + \lambda^* \{C_{y(2)}^2 + A_6 C_{x(2)}^2\} \right], \quad (32)$$



where  $A_5 = \frac{1}{2\delta_i} \left( \frac{1}{2\delta_i} - 2K_{yx} \right)$ ,  $A_6 = \frac{1}{2\delta_i} \left( \frac{1}{2\delta_i} - 2K_{yx(2)} \right)$  ( $i = 1, 2, 3, 4$ ),  $\delta_1 = \left( \frac{\bar{X} + S_x}{\bar{X}} \right)$ ,  
 $\delta_2 = \left( \frac{\bar{X} + C_x}{\bar{X}} \right)$ ,  $\delta_3 = \left( \frac{\bar{X} + \rho_{yx}}{\bar{X}} \right)$  and  $\delta_4 = \left( \frac{C_x \bar{X} + S_x}{C_x \bar{X}} \right)$ .

## 2.2 Situation II

The population mean  $\bar{X}$  is unknown, when non-response occurs on the study variable  $y$  and complete response on the auxiliary variable  $x$ . The estimator is given by:

$$\hat{Y}_{P(2)}^{(g)} = \bar{y}^* \exp \left( \frac{c(\bar{x}' - \bar{x})}{(c\bar{x}' + d) + (g-1)(c\bar{x} - d)} \right), \tag{33}$$

where ( $g > 0$ ).

Remark:

(i) When  $g = 0$ , the estimator  $\hat{Y}_{P(2)}^{(g)}$  reduces to

$$\hat{Y}_{P(2)}^{(0)} = \bar{y}^* \exp(1), \tag{34}$$

which is a biased estimator with larger *MSE* than the usual estimator  $\bar{y}^*$ .

(ii) When  $g = 1$ , the estimator  $\hat{Y}_{P(2)}^{(g)}$  reduces to

$$\hat{Y}_{P(2)}^{(1)} = \bar{y}^* \exp \left( \frac{c(\bar{x}' - \bar{x})}{c\bar{x}' + d} \right). \tag{35}$$

(iii) When  $g = 2$ , the estimator  $\hat{Y}_{P(2)}^{(g)}$  reduces to the estimator

$$\hat{Y}_{P(2)}^{(2)} = \bar{y}^* \exp \left( \frac{c(\bar{x}' - \bar{x})}{(c\bar{x}' + d) + (c\bar{x} + d)} \right). \tag{36}$$

To obtain bias and mean square error of  $\hat{Y}_{P(2)}^{(g)}$ , in terms of  $\varepsilon$ 's, we have:

$$\hat{Y}_{P(2)}^{(g)} = \bar{Y} (1 + \varepsilon_0) \exp \left( \frac{(\varepsilon_1' - \varepsilon_2)}{(\varepsilon_1' + (g-1)\varepsilon_2 - g\delta)} \right). \tag{37}$$

Solving (37), neglecting terms of  $\varepsilon$ 's and having power greater than two, we have:

$$\hat{Y}_{P(2)}^{(g)} \cong \bar{Y} \left[ \varepsilon_0 + \frac{1}{g\delta} (\varepsilon_1' - \varepsilon_2) + \frac{1}{g\delta} (\varepsilon_0 \varepsilon_1' - \varepsilon_0 \varepsilon_2) + \frac{1}{g^2 \delta^2} (\varepsilon_1' - \varepsilon_2)^2 - \frac{1}{g^2 \delta^2} (\varepsilon_1'^2 + (g-2)\varepsilon_1' \varepsilon_2 - (g-1)\varepsilon_2^2) \right]. \tag{38}$$

The bias of  $\hat{Y}_{P(2)}^{(g)}$ , to first order of approximation, is given by:

$$B(\hat{Y}_{P(2)}^{(g)}) \cong \bar{Y} \left[ \lambda'' \frac{1}{g\delta} \left\{ \frac{1}{g\delta} \left( g - \frac{1}{2} \right) - K_{yx} \right\} C_x^2 \right]. \quad (39)$$

Squaring both sides of (38) and neglecting terms of  $\varepsilon$ 's involving power greater than two, we have:

$$(T_{R(2)}^{(g)} - \bar{Y})^2 = \bar{Y}^2 \left[ \varepsilon_0^2 + \frac{1}{g^2\delta^2} (\varepsilon_1'^2 + \varepsilon_2^2 - 2\varepsilon_1'\varepsilon_2) + \frac{2}{g\delta} (\varepsilon_0\varepsilon_1' - \varepsilon_0\varepsilon_2) \right]. \quad (40)$$

Using (40), the mean square error of  $\hat{Y}_{P(2)}^{(g)}$  to the first degree of approximation is given by:

$$MSE(\hat{Y}_{P(2)}^{(g)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \left\{ C_y^2 + \frac{1}{g\delta} \left( \frac{1}{g\delta} - 2K_{yx} \right) C_x^2 \right\} + \lambda^* C_{y(2)}^2 \right]. \quad (41)$$

The  $MSE(\hat{Y}_{P(2)}^{(g)})$  is minimum when  $g = \frac{1}{\delta K_{yx}} = g_0$  (say).

Thus the resulting minimum  $MSE$  of  $\hat{Y}_{P(2)}^{(g)}$  is given by:

$$MSE(\hat{Y}_{P(2)}^{(g)})_{\min} \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda^* C_{y(2)}^2 + 2\lambda'' + C_y^2 \left( 1 - \rho_{yx}^2 \right) \right]. \quad (42)$$

In Table 2, for  $g = 1$  and  $g = 2$ , we propose a family of estimators  $\hat{Y}_{P(2)}^{(g)}$  of the population mean  $\bar{Y}$  by taking at different choices of  $c$  and  $d$  respectively. Many more estimators can also be generated from the proposed estimator in (33) just by putting different values of  $g$ ,  $c$  and  $d$ .

Using Table 2, the  $MSE$  of  $\hat{Y}_{P(2)}^{(1)(i)}$  and  $\hat{Y}_{P(2)}^{(2)(i)}$  ( $i = 1, 2, 3, 4$ ) to first degree of approximation are given by:

$$MSE(\hat{Y}_{P(2)}^{(1)(i)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \{ C_y^2 + A_3 C_x^2 \} + \lambda^* C_{y(2)}^2 \right], \quad (43)$$

and

$$MSE(\hat{Y}_{P(2)}^{(2)(i)}) \cong \bar{Y}^2 \left[ \lambda' C_y^2 + \lambda'' \{ C_y^2 + A_5 C_x^2 \} + \lambda^* C_{y(2)}^2 \right]. \quad (44)$$

**Table 2. Some members of a family of estimators  $\hat{Y}_{P(2)}^{(g)}$  under Situation-II.**

Estimator	$g$	$c$	$d$
$\hat{Y}_{P(2)}^{(1)(1)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}}{\bar{x}' + S_x}\right)$	1	1	$S_x$
$\hat{Y}_{P(2)}^{(1)(2)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}}{\bar{x}' + C_x}\right)$	1	1	$C_x$
$\hat{Y}_{P(2)}^{(1)(3)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}}{\bar{x}' + \rho_{yx}}\right)$	1	1	$\rho_{yx}$
$\hat{Y}_{P(2)}^{(1)(4)} = \bar{y}^* \exp\left(\frac{C_x(\bar{x}' - \bar{x})}{C_x\bar{x}' + S_x}\right)$	1	$C_x$	$S_x$
$\hat{Y}_{P(2)}^{(2)(1)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}}{(\bar{x}' + S_x) + (\bar{x} + S_x)}\right)$	2	1	$S_x$
$\hat{Y}_{P(2)}^{(2)(2)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}}{(\bar{x}' + C_x) + (\bar{x} + C_x)}\right)$	2	1	$C_x$
$\hat{Y}_{P(2)}^{(2)(3)} = \bar{y}^* \exp\left(\frac{\bar{x}' - \bar{x}}{(\bar{x}' + \rho_{yx}) + (\bar{x} + \rho_{yx})}\right)$	2	1	$\rho_{yx}$
$\hat{Y}_{P(2)}^{(2)(4)} = \bar{y}^* \exp\left(\frac{C_x(\bar{x}' - \bar{x})}{(C_x\bar{x}' + S_x) + (C_x\bar{x} + S_x)}\right)$	2	$C_x$	$S_x$

### 3. Efficiency comparisons

#### 3.1 Situation I

(a) When the constant 'h' is unknown:

To compare the estimator  $\hat{Y}_{P(1)}^{(h)}$  with the usual estimators  $\bar{y}^*$ ,  $\hat{Y}_{R(1)}$  and  $\hat{Y}_{Exp(1)}$  when the value of constant 'h' does not coincide with its optimum value ' $h_0$ ', we have

(i)  $Var(\bar{y}^*) - MSE(\hat{Y}_{P(1)}^{(h)}) > 0$  if  $h > \max\left\{\frac{1}{2\delta K_{yx}}, \frac{1}{2\delta K_{yx(2)}}\right\}$ .

(ii)  $MSE(\hat{Y}_{R(1)}) - MSE(\hat{Y}_{P(1)}^{(h)}) > 0$  if

$$\min \left\{ \frac{1}{\delta}, \frac{1}{\delta(2K_{yx} - 1)}, \frac{1}{\delta(2K_{yx(2)} - 1)} \right\} < h < \max \left\{ \frac{1}{\delta}, \frac{1}{\delta(2K_{yx} - 1)}, \frac{1}{\delta(2K_{yx(2)} - 1)} \right\}.$$

(iii)  $MSE(\hat{Y}_{Exp(1)}) - MSE(\hat{Y}_{P(1)}^{(h)}) > 0$  if

$$\min \left\{ \frac{2}{\delta}, \frac{2}{\delta(4K_{yx} - 1)}, \frac{2}{\delta(4K_{yx(2)} - 1)} \right\} < h < \max \left\{ \frac{2}{\delta}, \frac{2}{\delta(4K_{yx} - 1)}, \frac{2}{\delta(4K_{yx(2)} - 1)} \right\}.$$

(b) When the constant 'h' is known:

(i)  $Var(\bar{y}^*) - MSE(\hat{Y}_{P(1)}^{(h)})_{\min} > 0$  if  $\frac{(\lambda''K_{yx}C_x^2 + \lambda^*K_{yx(2)}C_{x(2)}^2)^2}{\lambda''C_x^2 + \lambda^*C_{x(2)}^2} > 0$ .

(ii)  $MSE(\hat{Y}_{R(1)}) - MSE(\hat{Y}_{P(1)}^{(h)})_{\min} > 0$  if

$$\left( \frac{(\lambda''K_{yx}C_x^2 + \lambda^*K_{yx(2)}C_{x(2)}^2)^2}{\lambda''C_x^2 + \lambda^*C_{x(2)}^2} + \lambda''(1 - 2K_{yx})C_x^2 \right) > 0 \text{ and } K_{yx(2)} < \frac{1}{2}.$$

(iii)  $MSE(\hat{Y}_{Exp(1)}) - MSE(\hat{Y}_{P(1)}^{(h)})_{\min} > 0$  if

$$\left( \frac{(\lambda''K_{yx}C_x^2 + \lambda^*K_{yx(2)}C_{x(2)}^2)^2}{\lambda''C_x^2 + \lambda^*C_{x(2)}^2} + \lambda''\left(\frac{1}{4} - K_{yx}\right)C_x^2 \right) > 0 \text{ and } K_{yx(2)} < \frac{1}{4}.$$

(iv)  $MSE(\hat{Y}_{Reg(1)}) - MSE(\hat{Y}_{P(1)}^{(h)})_{\min} > 0$  if

$$\left( \frac{(\lambda''K_{yx}C_x^2 + \lambda^*K_{yx(2)}C_{x(2)}^2)^2}{\lambda''C_x^2 + \lambda^*C_{x(2)}^2} - \lambda''\rho_{yx}^2C_y^2 \right) > 0 \text{ and } K_{yx} > 2K_{yx(2)}.$$

### 3.2 Situation II

(a) When the constant 'g' is unknown:

To compare the estimator  $\hat{Y}_{P(2)}^{(g)}$  with the usual estimators  $\bar{y}^*$ ,  $\hat{Y}_{R(2)}$  and  $\hat{Y}_{Exp(2)}$  when the value of constant 'g' does not coincide with its optimum value 'g<sub>0</sub>', we have

(i)  $Var(\bar{y}^*) - MSE(\hat{Y}_{P(2)}^{(g)}) > 0$  if  $g > \frac{1}{2\delta K_{yx}}$ .

(ii)  $MSE(\hat{Y}_{R(2)}) - MSE(\hat{Y}_{P(2)}^{(g)}) > 0$  if

$$\min \left\{ \frac{1}{\delta}, \frac{1}{\delta(2K_{yx} - 1)} \right\} < g < \max \left\{ \frac{1}{\delta}, \frac{1}{\delta(2K_{yx} - 1)} \right\}.$$

(iii)  $MSE(\hat{Y}_{Exp(2)}) - MSE(\hat{Y}_{P(2)}^{(g)}) > 0$  if

$$\min \left\{ \frac{2}{\delta}, \frac{2}{\delta(4K_{yx} - 1)} \right\} < g < \max \left\{ \frac{2}{\delta}, \frac{2}{\delta(4K_{yx} - 1)} \right\}.$$

(b) When the constant 'g' is known:

(i)  $Var(\bar{y}^*) - MSE(\hat{Y}_{P(2)}^{(g)})_{\min} > 0$  if  $K_{yx} > 0$ .

(ii)  $MSE(\hat{Y}_{R(2)}) - MSE(\hat{Y}_{P(2)}^{(g)})_{\min} > 0$  if  $K_{yx} < 1$  and  $K_{yx} > 1$ .

(iii)  $MSE(\hat{Y}_{Exp(2)}) - MSE(\hat{Y}_{P(2)}^{(g)})_{\min} > 0$  if  $K_{yx} < \frac{1}{2}$  and  $K_{yx} > \frac{1}{2}$ .

(iv)  $MSE(\hat{Y}_{Reg(2)}) - MSE(\hat{Y}_{P(2)}^{(g)})_{\min} = 0$ .

The proposed estimators in Situations I and II are more efficient than the other considered estimators if above conditions are satisfied.

#### 4. Empirical study

We use two data sets for efficiency comparison.

**Population 1:** (source: Khare and Sinha [7])

The data on physical growth of upper socio-economic group of 95 school children of Varanasi under an ICMR study, department of Pediatrics, B. H.U., during 1983-84 has been taken under study. The first 25% (i.e. 24 children) units have been considered as non-responding units.

Let  $y$  = Weights (kg) of children and  $x$  = Skull circumference (cm) of the children.

For this population, we have:

$$N = 95, n' = 70, n = 35, W_2 = 0.25, \bar{Y} = 19.4968, \bar{X} = 51.1726, C_y = 0.15613, C_{y(2)} = 0.12075,$$

$$C_x = 0.03006, C_{x(2)} = 0.02478, \rho_{yx} = 0.328, \rho_{yx(2)} = 0.477.$$

**Population-II:** (Source: Murthy [8])

Consider the data on number of workers and output for 80 factories in a region. The middle 20% units in the population have been treated as non-responding units.

Let  $y$  = output and  $x$  = number of workers in the factory.

For this population, we have:

$$N = 80, n' = 45, n = 20, W_2 = 0.20, \bar{Y} = 5182.64, \bar{X} = 285.125, C_y = 0.35419, C_{y(2)} = 0.07110,$$

$$C_x = 0.94846, C_{x(2)} = 0.08519, \rho_{yx} = 0.914, \rho_{yx(2)} = 0.691.$$

We have computed the percent relative efficiency (*PRE*) of different estimators with respect to usual unbiased estimator  $\bar{y}^*$  for different values of  $k$ .

**Table 3.** *PRE* of different estimators with respect to  $\bar{y}^*$  for different values of  $k$  under Situation-I.

Estimator	Population-I				Population-II			
	(1/k)				(1/k)			
	(1/5)	(1/4)	(1/3)	(1/2)	(1/5)	(1/4)	(1/3)	(1/2)
$\bar{y}^*$	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
$\hat{Y}_{P(1)}^{(1)(1)}$	112.21	111.49	110.55	109.28	209.91	208.98	208.03	207.07
$\hat{Y}_{P(1)}^{(1)(2)}$	112.48	111.74	110.78	109.47	40.56	40.19	39.81	39.44
$\hat{Y}_{P(1)}^{(1)(3)}$	112.43	111.69	110.73	109.43	40.55	40.18	39.81	39.44
$\hat{Y}_{P(1)}^{(1)(4)}$	106.88	106.52	106.05	105.40	219.38	218.51	217.63	216.73
$\hat{Y}_{P(1)}^{(2)(1)}$	106.70	106.35	105.89	105.26	250.66	251.59	252.55	253.54
$\hat{Y}_{P(1)}^{(2)(2)}$	106.84	106.52	106.04	105.40	220.57	219.71	218.83	217.94
$\hat{Y}_{P(1)}^{(2)(3)}$	106.84	106.48	106.01	105.36	220.56	219.70	218.82	217.93
$\hat{Y}_{P(1)}^{(2)(4)}$	103.57	103.39	103.16	102.84	246.36	247.27	248.22	249.19
$\hat{Y}_{R(1)}$	112.49	111.75	110.78	109.47	38.36	38.08	37.79	37.52
$\hat{Y}_{Reg(1)}$	117.17	115.95	114.38	112.27	256.22	257.68	259.18	260.73
$\hat{Y}_{Exp(1)}$	106.88	106.52	106.05	105.40	193.96	194.02	194.08	194.14
$\hat{V}(h)$	117.80	116.41	114.65	112.37	256.25	257.69	259.19	260.73

In Table 3 under Population-I, it is observed that the *PRE* of all estimators decreases as the value of  $(1/k)$  increases. In this table under Population-II, the estimators  $\hat{Y}_{P(1)}^{(1)(2)}$ ,  $\hat{Y}_{P(1)}^{(1)(3)}$  and  $\hat{Y}_{R(1)}$  show the poor performances as compared to all other considered estimators. Also under Population-II, the *PRE* of estimators  $\hat{Y}_{P(1)}^{(2)(2)}$ ,  $\hat{Y}_{P(1)}^{(2)(4)}$ ,  $\hat{Y}_{Reg(1)}$ ,  $\hat{Y}_{Exp(1)}$  and  $\hat{Y}_{P(1)}$  increases as the value of  $(1/k)$  increases whilst *PRE* of estimators  $\hat{Y}_{P(1)}^{(1)(1)}$ ,  $\hat{Y}_{P(1)}^{(2)(2)}$  and  $\hat{Y}_{P(1)}^{(2)(3)}$  decreases as the value of  $(1/k)$  increases.

In Table 4, *PRE* of all estimators increases as the value of  $(1/k)$  increases under both Populations I and II except in Population-II where the estimators  $\hat{Y}_{P(2)}^{(1)(2)}$ ,  $\hat{Y}_{P(2)}^{(1)(3)}$ ,  $\hat{Y}_{R(2)}$  perform badly.

**Table 4. PRE of different estimators with respect to  $\bar{y}^*$  for different values of  $k$  under Situation-II.**

Estimator	Population-I				Population-II			
	(1/k)				(1/k)			
	(1/5)	(1/4)	(1/3)	(1/2)	(1/5)	(1/4)	(1/3)	(1/2)
$\bar{y}^*$	100.00	100.00	100.00	100.00	100.00	100.00	100.00	100.00
$\hat{Y}_{P(2)}^{(1)(1)}$	103.70	104.23	104.94	105.95	197.46	199.49	201.60	203.80
$\hat{Y}_{P(2)}^{(1)(2)}$	103.76	104.31	105.03	106.06	40.07	39.83	39.57	39.32
$\hat{Y}_{P(2)}^{(1)(3)}$	103.75	104.30	105.02	106.05	40.07	39.83	39.57	39.32
$\hat{Y}_{P(2)}^{(1)(4)}$	102.24	102.56	102.98	103.57	205.99	208.29	210.69	213.20
$\hat{Y}_{P(2)}^{(2)(1)}$	102.18	102.49	102.91	103.48	239.32	242.84	246.54	250.44
$\hat{Y}_{P(2)}^{(2)(2)}$	102.24	102.56	102.98	103.57	207.06	209.39	211.83	214.37
$\hat{Y}_{P(2)}^{(2)(3)}$	102.23	102.54	102.97	103.55	207.05	209.38	211.82	214.36
$\hat{Y}_{P(2)}^{(2)(4)}$	101.20	101.37	101.60	101.91	235.61	238.98	242.52	246.26
$\hat{Y}_{R(2)}$	103.77	104.31	105.04	106.06	38.22	37.98	37.73	37.48
$\hat{Y}_{Reg(2)}$	104.57	105.24	106.14	107.40	245.89	249.68	253.67	257.89
$\hat{Y}_{Exp(2)}$	102.24	102.56	102.98	103.57	186.95	188.65	190.43	192.28
$\hat{Y}_{\hat{g}}$	104.57	105.24	106.14	107.40	245.89	249.68	253.67	257.89

From Tables 3 and 4, it is observed that the proposed estimators  $\hat{Y}_{P(2)}^{(h)}$  and  $\hat{Y}_{P(2)}^{(g)}$  are more efficient as compared to the usual Hansen and Hurwitz [3] estimator, classical ratio, exponential-ratio type estimators and all other considered estimators in their respective situations under optimum conditions. It is also observed that the difference between  $\hat{Y}_{P(1)}^{(h)}$  and  $\hat{Y}_{Reg(1)}$  is either small or equal in Situation-I and are equally efficient in Situation-II. Overall Situation-I is preferable as compared to Situation-II.

From the range of constants i.e. ( $h$  and  $g$ ) in efficiency comparisons, it has been observed that the proposed estimators  $\hat{Y}_{P(1)}^{(h)}$  and  $\hat{Y}_{P(2)}^{(g)}$  are more desirable over all the considered estimators even if the guessed values of the scalars ' $h$ ' and ' $g$ ' depart substantially from the exact optimum values i.e. ' $h_0$ ' and ' $g_0$ ' respectively.

## 5. Conclusion

We have developed a general class of exponential ratio type estimators under two different situations of nonresponse. Theoretical and numerical comparisons show that the proposed class of estimators  $\hat{Y}_{P(1)}^{(h)}$  and  $\hat{Y}_{P(2)}^{(g)}$  are more efficient than the estimators  $\bar{y}^*$ ,  $\hat{Y}_{R(i)}$  and  $\hat{Y}_{EXP(i)}$  ( $i = 1, 2$ ) for both data sets. In Table 4,  $\hat{Y}_{P(2)}^{(g)}$  is exactly equal to the regression estimator  $\hat{Y}_{Reg(2)}$ .

## Acknowledgement

Authors are thankful to the learned referees for their valuable suggestions to improve the manuscript.

## References

- [1]. Bahl, S., and Tuteja, R. K. (1991). Ratio and product type exponential estimator, *Information and Optimization Sciences*, 12, 159-163.
- [2]. Cochran, W. G. (1977). *Sampling Techniques*, (3rd ed.). John Wiley and Sons, New York.
- [3]. Hansen, M. H., and Hurwitz, W. N. (1946). The problem of non response in sample surveys. *Journal of the American Statistical Association*, 41, 517-529.
- [4]. Khare, B.B., and Srivastava, S. (1993). Estimation of population mean using auxiliary characters in the presence of non-response. *National Academy Science Letters*, India 16(3), 111-114.
- [5]. Khare, B.B., and Srivastava, S. (1995). Study of conventional and alternative two phase sampling ratio, product and regression estimators in the presence of non-response. *Proceedings of the Indian National Science Academy*, 16(A), II: 195-203.
- [6]. Khare, B.B., and Srivastava, S. (1997). Transformed ratio type estimators for the population mean in the presence of non-response. *Communication in Statistics- Theory and Methods*, 26(7), 1779-1791.
- [7]. Khare, B.B., and Sinha, R. R. (2007). Estimation of the ratio of the two population means using multi auxiliary characters in the presence of non-response. *Statistical Techniques in Life Testing, Reliability, Sampling Theory and Quality Control*, 163-171.
- [8]. Murthy, M.N. (1967). *Sampling Theory and Methods*. Statistical Publication Society: India.
- [9]. Okafor, F. C., and Lee, H. (2000). Double sampling for ratio and regression estimation with sub sampling the non-respondent. *Survey Methodology*, 26(2), 183-188.
- [10]. Rao, P.S.R.S., (1986). Ratio and regression estimates with sub sampling the non-respondents, *Papers presented at a special contributed session of the International Statistical Association Meeting*, Sept., Tokyo, Japan, 2-16.
- [11]. Rao, P.S.R.S., (1987). Ratio estimation with sub sampling the non-respondents. *Survey Methodology*, 12(2), 217-230.
- [12]. Sarndal C. E., and Lundstrom S. (2005). *Estimation in Survey Sampling with Non-Response*. New York: John Wiley and Sons.



- [13]. Singh, H. P., and Kumar, S. (2008a). A regression approach to the estimation of the finite population mean in the presence of non-response. *Australian and New Zealand Journal of Statistics*, 50(4), 395-402.
- [14]. Singh, H. P., and Kumar, S. (2008b). A general family of estimators of the finite population ratio, product and mean using two phase sampling scheme in the presence of non-response. *Journal of Statistical Theory and Practice*, 2(4), 677-692.
- [15]. Singh, H. P., and Kumar, S. (2009a). A general class of estimators of the population mean in survey sampling using auxiliary information with sub sampling the non-respondents. *Korean Journal of Applied Statistics*, 22(2), 387-402.
- [16]. Singh, H. P., and Kumar, S. (2009b). A general procedure of estimating the population mean in the presence of non- response under double sampling using auxiliary information. *SORT*, 33(1), 71-84.
- [17]. Singh, H. P., and Kumar, S. (2010a). Estimation of mean in the presence of non-response using two phase sampling scheme. *Statistical Papers*, 51, 559-582.
- [18]. Singh, H. P., and Kumar, S. (2010b). Improved estimation of population mean under double sampling with sub-sampling the non-respondents. *Journal of Statistical Planning and Inference*, 140(9), 2536-2550.
- [19]. Singh, H. P., Kumar, S., and Kozak, M. (2010). Improved estimation of finite population mean using sub-sampling to deal with non-response in two-phase sampling scheme. *Communication in Statistic-Theory and Methods*, 39(5), 791-802.
- [20]. Tabasum, R., and Khan, I. A. (2004). Double sampling for ratio estimation with non-response. *Journal of the Indian Society of Agricultural Statistics*, 58(3), 300-306.
- [21]. Tabasum, R., and Khan, I. A. (2006). Double sampling ratio estimator for the population mean in presence of non-response. *Assam Statistics Review*, 20, 73-83.
- [22]. Upadhyaya, L.N., Singh, H.P., Chatterjee, S. and Yadav, R. (2011). Improved ratio and product exponential type estimators. *Journal of Statistical Theory and Practice*, 5(2), 285-302.